### Information-Theoretic Clustering in Nonlinear Encoder Models

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July 4, 2005

### **Overview**

Information-theoretic clustering in encoder models:

- conceptually simple
- probabilistic (soft)
- kernelizable and applicable to unsupervized learning of kernel functions
- computationally attractive (no need to compute eigenvalues or inverses of the Gram matrix)
- favorably compares with common clustering methods in some cases

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Work in progress...

# **Clarifying the definitions**

What is a cluster?

- "Cluster's members should be close to each other"
- "Bunch's organs should shut together" (automatic translation into Russian and back)
- "A cluster is something found by a clustering algorithm" (an anonymous machine learner)

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- a set whose members should satisfy local smoothness constraints (need to constrain the model)
- it is undesirable to assign unique labels to outliers (high marginal entropy of cluster labels?)

## Encoder vs Generative Models

Let  $x \in \mathbb{R}^{|x|}$  be a visible pattern, and  $y \in \{y_1, \dots, y_{|y|}\}$  its discrete unknown cluster label



- generative models:  $\mathcal{M}_L \stackrel{\text{def}}{=} p(\mathbf{y}) p(\mathbf{x}|\mathbf{y})$
- maximizing the likelihood  $\mathcal{L} = \log p(\mathbf{x}^{(1)}, \dots, \mathbf{x}^{(M)})$
- problems with under-constrained models

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- encoder models:  $\mathcal{M}_I \stackrel{\text{def}}{=} \tilde{p}(\mathbf{x}) p(\mathbf{y}|\mathbf{x})$
- an "unsupervised discriminative" framework
- maximizing the likelihood is meaningless...

# Information-Theoretic Clustering

- Goal: learn a mapping  $x \rightarrow y$
- interprete cluster labels y as unknown codes
- maximize coding efficiency

$$I(\mathbf{x}, y) \stackrel{\text{def}}{=} H(\mathbf{x}) - H(\mathbf{x}|y) \equiv H(y) - H(y|\mathbf{x})$$

- $H(y) \equiv -\langle \log p(y) \rangle_{p(y)}, H(y|\mathbf{x}) \equiv -\langle \log p(y|\mathbf{x}) \rangle_{p(y|\mathbf{x})\tilde{p}(\mathbf{x})}, \tilde{p}(\mathbf{x})$  is the empirical distribution
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- (Arimoto, Blahut '72; Linsker '88)
- Generally quite difficult (entropy of a mixture H(y))...
- but tractable for clustering

# Information-Theoretic Clustering: Motivation

Generative vs encoder models: what is more attractive?

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- a poor fit to curved manifolds unless |y| is large

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Encoder models:

- $p(y|\mathbf{x})$  may be very complex
- I(x, y) = H(y) H(y|x) implicitly favors *equiprobable deterministic* cluster assignments

# **Learning Optimal Parameters**

- Constrain  $p(y|\mathbf{x})$  to satisfy local smoothness
- A simple choice of the encoder is

 $p(y_j|\mathbf{x}^{(i)}) \propto \exp\{-\|\mathbf{x}^{(i)} - \mathbf{w}_j\|^2 / s_j + b_j\},\$ 

(probability of assigning  $x^{(i)}$  to cluster  $y_j$ )

maximize *I*(x, y) for cluster centers w<sub>j</sub> ∈ ℝ<sup>|x|</sup>, dispersions s<sub>j</sub>,
 and biases b<sub>j</sub>

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- maximize *I*(x, y) for cluster centers w<sub>j</sub> ∈ ℝ<sup>|x|</sup>, dispersions s<sub>j</sub>,
  and biases b<sub>j</sub>
- $p(y|\mathbf{x})$  is similar to the posterior of Gaussian mixtures
- $\mathcal{M}_I = \tilde{p}(\mathbf{x})p(y|\mathbf{x})$  is trained by maximizing  $I(\mathbf{x}, y)$

# Learning Optimal Parameters (Cont.)

• Nonlinear ascent on I(x, y) with

$$\frac{\partial I(\mathbf{x}, y)}{\partial \mathbf{w}_j} = \frac{1}{M} \sum_{m=1}^M p(y_j | \mathbf{x}^{(m)}) \frac{(\mathbf{x}^{(m)} - \mathbf{w}_j)}{s_j} \alpha_j^{(m)}$$

$$\frac{\partial I(\mathbf{x}, y)}{\partial s_j} = \frac{1}{M} \sum_{m=1}^M p(y_j | \mathbf{x}^{(m)}) \frac{\|\mathbf{x}^{(m)} - \mathbf{w}_j\|^2}{2s_j^2} \alpha_j^{(m)}$$

• Coefficients  $\alpha_j^{(m)}$ :

$$\alpha_j^{(m)} \stackrel{\text{def}}{=} \log \frac{p(\mathbf{x}^{(m)}|y_j)}{p(\mathbf{x}^{(m)})} - KL\left(p(y|\mathbf{x}^{(m)}) \| \langle p(y|\mathbf{x}) \rangle_{\tilde{p}(\mathbf{x})}\right)$$

• (*cf* ML for mixtures of Gaussians)

# **Clustering in Nonlinear Encoder Models**

Nonlinear encoders:

$$p(y_j|\mathbf{x}^{(i)}) \propto \exp\{-\|\boldsymbol{\phi}(\mathbf{x}^{(i)}) - \mathbf{w}_j\|^2/s_j + b_j\},\$$

- $\phi(\mathbf{x}^{(i)}) \in \mathbb{R}^{|\phi|}$  is a *feature* vector for pattern  $\mathbf{x}^{(i)}$
- $|\phi|$  may be  $\infty$ -dimensional.
- x<sup>(i)</sup>, x<sup>(k)</sup> are likely to be clustered as y<sub>j</sub> if they lie close to an unknown cluster center w<sub>j</sub> in a *feature space*

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#### • Kernelization is straight-forward:

$$\mathsf{K} \stackrel{\text{def}}{=} \{ K_{ij} \} \stackrel{\text{def}}{=} \{ \boldsymbol{\phi}(\mathsf{x}^{(i)})^T \boldsymbol{\phi}(\mathsf{x}^{(j)}) \} = \mathcal{K}(\boldsymbol{\Theta}) \in \mathbb{R}^{M \times M}$$

•  $\mathbf{w}_j = \sum_{m=1}^M \alpha_{mj} \boldsymbol{\phi}(\mathbf{x}^{(m)}) + \mathbf{w}_j^{\perp}$ , where  $(\mathbf{w}_j^{\perp})^T \boldsymbol{\phi}(\mathbf{x}^{(m)}) = 0$ 

- maximize  $I(\mathbf{x}, y)$  for  $\{\alpha_{jm}\}$ ,  $s_j$ ,  $b_j$ , and kernel parameters  $\Theta$
- (Again, numerical ascent on I(x, y))

# Learning Kernels

$$\frac{\partial I(\mathbf{x}, y)}{\partial \Theta} = \frac{1}{M} \sum_{m=1}^{M} KL(p(y|\mathbf{x}^{(m)}) || p(y)) \sum_{k=1}^{|y|} \frac{\partial f_k(\mathbf{x}^{(m)})}{\partial \Theta} p(y_k|\mathbf{x}^{(m)}) - \frac{1}{M} \sum_{m=1}^{M} \sum_{j=1}^{|y|} \frac{\partial f_j(\mathbf{x}^{(m)})}{\partial \Theta} p(y_j|\mathbf{x}^{(m)}) \log \frac{p(y_j|\mathbf{x}^{(m)})}{p(y_j)}$$

• 
$$p(y_j|\mathbf{x}^{(m)}) \propto \exp\{-f_j(\mathbf{x}^{(m)})\}$$

• potentials  $f_j(\mathbf{x}^{(m)})$ :

$$f_j(\mathbf{x}^{(m)}) \equiv \left\{ -\left(K_{mm} - 2\mathbf{k}^T(\mathbf{x}^{(m)})\mathbf{a}_j + \mathbf{a}_j^T\mathbf{K}\mathbf{a}_j + c_j\right)/s_j \right\}$$

• numerical ascent on  $I(\mathbf{x}, y) \sim O(M|y|^2)$ 

• no need to compute eigenvalues of  $\mathsf{K} \in \mathbb{R}^{M \times M}$ 

### **Experiments**:



- Clustering:  $p(y_j | \mathbf{x}^{(i)}) \propto \{-\| \boldsymbol{\phi}(\mathbf{x}^{(i)}) \mathbf{w}_j \|^2 / s_j \}$
- unsupervised clustering, nonlinear encoder
- favorably compares with GMMs, k-means, kernel k-means, normalized cuts [Ng et. al. '01], non-kernelized MI, fixed-kernel KMI

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# Summary

- unsupervised information-theoretic clustering
- extracts clusters directly from the dataset
- conceptually simple
- suggests a principled way to learn the kernels
- potentially generalizable to other encoder models

Still need: practical applications; theoretical analysis (links to wheighted annealed feature-space k-means?)